## **SIEMENS**

## **Data sheet**

## 6ES7512-1DM03-0AB0



SIMATIC DP, CPU 1512SP-1 PN for ET 200SP, central processing unit with work memory 400 KB for program and 2 MB for data, 1st interface: PROFINET IRT with 3-port switch, 25 ns bit performance, SIMATIC Memory Card required, BusAdapter required for port 1 and 2

Figure similar

Ganaral information	
General information	ODU 45400D 4 DN
Product type designation	CPU 1512SP-1 PN
HW functional status	FS03
Firmware version	V3.1
FW update possible	Yes
Product function	
I&M data	Yes; I&M0 to I&M3
<ul> <li>Module swapping during operation (hot swapping)</li> </ul>	Yes; Multi-hot swapping
<ul> <li>Isochronous mode</li> </ul>	Yes; only with PROFINET; with minimum OB 6x cycle of 500 μs
SysLog	Yes
Engineering with	
STEP 7 TIA Portal configurable/integrated from version	V19 (FW V3.1) / V18 (FW V3.0) or higher; with older TIA Portal versions configurable as 6ES7 512-1DK01-0AB0
Configuration control	
via dataset	Yes
Control elements	
Mode selector switch	1
Supply voltage	
Rated value (DC)	24 V
permissible range, lower limit (DC)	19.2 V
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
<ul> <li>Mains/voltage failure stored energy time</li> </ul>	10 ms
Input current	
Current consumption (rated value)	0.48 A
Current consumption, max.	0.7 A
Inrush current, max.	1.34 A; Rated value
I <sup>2</sup> t	0.3 A²-s
Power	
Infeed power to the backplane bus	8.05 W
Power loss	
Power loss, typ.	3.5 W
Memory	
Number of slots for SIMATIC memory card	1
SIMATIC memory card required	Yes
Work memory	
• integrated (for program)	400 kbyte
• integrated (for data)	2 Mbyte

Retentivity adjustable	Yes
Retentivity adjustable     Retentivity preset	No
Local data	110
• per priority class, max.	64 kbyte; max. 16 KB per block
Address area	C. Royto, max. 10 No por blook
Number of IO modules	2 048; max. number of modules / submodules
I/O address area	
• Inputs	32 kbyte; All inputs are in the process image
• Outputs	32 kbyte; All outputs are in the process image
per integrated IO subsystem	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
per CM/CP	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	
Number of subprocess images, max.	32
Address space per module	
Address space per module, max.	288 byte; For input and output data respectively
Address space per station	
<ul> <li>Address space per station, max.</li> </ul>	2 560 byte; for central inputs and outputs; depending on configuration; 2 048 bytes for ET 200SP modules + 512 bytes for ET 200AL modules
Hardware configuration	2, 30 Tot ET 20001 HISBARD - 012 bytes for ET 200AE HISBARD
Number of distributed IO systems	32; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also
	by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of DP masters	
• Via CM	1
Number of IO Controllers	
• integrated	1
• Via CM	0
Rack	92: CDI I 64 modulos I como modulo (mounties middle escribites and an) 40 FT
Modules per rack, max.  Overtity of coursels ET 2000B modules, may	82; CPU + 64 modules + server module (mounting width max. 1 m) + 16 ET 200AL modules
Quantity of operable ET 200SP modules, max.      Quantity of operable ET 200AL modules, max.	64
Quantity of operable ET 200AL modules, max.     Number of lines, max.	16 1
Number of lines, max.  PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available
THURSON OF LE CIVIS	slots
Time of day	
Clock	
• Type	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Operating hours counter	
Number	16
Clock synchronization	
• supported	Yes
• to DP, master	Yes; Via CM DP module
• on DP, device	Yes; Via CM DP module
• in AS, master	Yes
• in AS, device	Yes
on Ethernet via NTP	Yes
Interfaces	
Number of PROFINET interfaces	1
Number of PROFIBUS interfaces Optical interfaces	1; Via CM DP module
Optical interface	No
1. Interface	
Interface types	Vec. V1 D3: ant V1 D1 and V1 D2 via BucAdapter DA 3v D I45
RJ 45 (Ethernet)     Number of ports	Yes; X1 P3; opt. X1 P1 and X1 P2 via BusAdapter BA 2x RJ45
Number of ports	3; 1. integr. + 2. via BusAdapter

<ul> <li>integrated switch</li> </ul>	Yes
<ul><li>BusAdapter (PROFINET)</li></ul>	Yes; compatible BusAdapters: BA 2x RJ45, BA 2x M12, BA 2x FC, BA 2x LC, BA LC/RJ45, BA LC/FC, BA 2x SCRJ, BA SCRJ/RJ45, BA SCRJ/FC
Protocols	BA EGING43, BA EGILO, BA 2X 30N3, BA 30N3/N343, BA 30N3/N 0
IP protocol	Yes; IPv4
PROFINET IO Controller	Yes
PROFINET IO Device	Yes
SIMATIC communication	Yes
Open IE communication	Yes; Optionally also encrypted
Web server	Yes
Media redundancy	Yes
PROFINET IO Controller	
Services	
— Isochronous mode	Yes
<ul> <li>Direct data exchange</li> </ul>	Yes; Requirement: IRT and isochronous mode (MRPD optional)
— IRT	Yes
— PROFlenergy	Yes; per user program
— Prioritized startup	Yes; Max. 32 PROFINET devices
— Number of connectable IO Devices, max.	128; In total, up to 512 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
— Of which IO devices with IRT, max.	64
<ul> <li>Number of connectable IO Devices for RT, max.</li> </ul>	128
— of which in line, max.	128
<ul> <li>Number of IO Devices that can be simultaneously activated/deactivated, max.</li> </ul>	8; in total across all interfaces
— Number of IO Devices per tool, max.	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
— PROFINET Security Class	1
Update time for IRT	
— for send cycle of 250 μs	250 µs to 4 ms; Note: In the case of IRT with isochronous mode, the minimum
	update time of 500 μs of the isochronous OB is decisive
— for send cycle of 500 μs	500 μs to 8 ms
— for send cycle of 1 ms	1 ms to 16 ms
— for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
<ul> <li>With IRT and parameterization of "odd" send cycles</li> </ul>	Update time = set "odd" send clock (any multiple of 125 $\mu$ s: 375 $\mu$ s, 625 $\mu$ s 3 875 $\mu$ s)
Update time for RT	
— for send cycle of 250 μs	250 μs to 128 ms
— for send cycle of 500 μs	500 μs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
PROFINET IO Device	
Services	
— Isochronous mode	No
— IRT	Yes
— PROFlenergy	Yes; per user program
— Shared device	Yes
Number of IO Controllers with shared device, max.	4
activation/deactivation of I-devices	Yes; per user program
— Asset management record	Yes; per user program
— PROFINET Security Class	SNMP Configuration and DCP Read Only
2. Interface	
Interface types	Vac Via CM DD modula
• RS 485	Yes; Via CM DP module
Number of ports  Protocols	1
Protocols  • PROFIBLIS DR moster	Voc
PROFIBUS DP master     PROFIBUS DP dovices	Yes
<ul><li>PROFIBUS DP device</li><li>SIMATIC communication</li></ul>	Yes Yes
SHVIATIO COMMUNICATION	100

PROFIBUS DP master	
Number of connections, max.	48; Of which 4 each reserved for ES and HMI
• max. number of DP devices	125; In total, up to 512 distributed I/O devices can be connected via AS-i,
	PROFIBUS or PROFINET
Services	
— Equidistance	No
— Isochronous mode	No
activation/deactivation of DP devices	Yes
nterface types	
RJ 45 (Ethernet)	
• 100 Mbps	Yes
Autonegotiation	Yes
Autocrossing	Yes
Industrial Ethernet status LED	Yes
RS 485	40.40.70
Transmission rate, max.	12 Mbit/s
Protocols	
PROFIsafe	No
Number of connections	
Number of connections, max.	128; via integrated interfaces of the CPU and connected CPs / CMs
Number of connections reserved for ES/HMI/web	10
Number of connections via integrated interfaces	88
Number of connections per CP/CM	32
Number of S7 routing paths	16
Redundancy mode	V
H-Sync forwarding	Yes
Media redundancy	V 1 2 2 4 1 1
— Media redundancy	Yes; only via BusAdapter
— MRP	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client
- MRP interconnection, supported	Yes; as MRP ring node according to IEC 62439-2 Edition 3.0
— MRPD	Yes; Requirement: IRT
Switchover time on line break, typ.	200 ms; For MRP, bumpless for MRPD
Number of stations in the ring, max.	50
SIMATIC communication	
PG/OP communication	Yes; encryption with TLS V1.3 pre-selected
S7 routing	Yes
Data record routing	Yes
S7 communication, as server	Yes
S7 communication, as client	Yes
User data per job, max.	See online help (S7 communication, user data size)
Open IE communication	, , , , , , , , , , , , , , , , , , , ,
• TCP/IP	Yes
— Data length, max.	64 kbyte
several passive connections per port, supported	Yes
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
• UDP	Yes
— Data length, max.	2 kbyte; 1 472 bytes for UDP broadcast
— UDP multicast	Yes; max. 78 multicast circuits
• DHCP	Yes
• DNS	Yes
• SNMP	Yes
• DCP	Yes
• LLDP	Yes
Encryption	Yes; Optional
Web server	
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
• web API	

number of simultaneous HTTD calls, may	4
— number of simultaneous HTTP calls, max.	4
— HTTP request body, max.  OPC UA	131 072 byte
Runtime license required	Yes; "Small" license required
OPC UA Client	Yes; Data Access (registered Read/Write), Method Call
Application authentication	Yes
Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15,
,	Basic256Sha256
<ul><li>User authentication</li></ul>	"anonymous" or by user name & password
<ul> <li>Number of connections, max.</li> </ul>	4
<ul> <li>Number of nodes of the client interfaces, recommended max.</li> </ul>	1 000
<ul> <li>Number of elements for one call of OPC_UA_NodeGetHandleList/OPC_UA_ReadList/OPC_I max.</li> </ul>	300
<ul> <li>Number of elements for one call of OPC_UA_NameSpaceGetIndexList, max.</li> </ul>	20
<ul> <li>Number of elements for one call of OPC_UA_MethodGetHandleList, max.</li> </ul>	100
<ul> <li>Number of simultaneous calls of the client instructions for session management, per connection, max.</li> </ul>	1
<ul> <li>Number of simultaneous calls of the client instructions for data access, per connection, max.</li> </ul>	5
<ul> <li>Number of registerable nodes, max.</li> </ul>	5 000
<ul> <li>Number of registerable method calls of OPC_UA_MethodCall, max.</li> </ul>	100
<ul><li>— Number of inputs/outputs when calling OPC_UA_MethodCall, max.</li></ul>	20
OPC UA Server	Yes; Data Access (Read, Write, Subscribe), Method Call, Alarms & Condition (A&C), Custom Address Space
<ul> <li>Application authentication</li> </ul>	Yes
— Security policies	available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256, Aes128Sha256RsaOaep, Aes256Sha256RsaPss
— User authentication	"anonymous" or by user name & password
GDS support (certificate management)	Yes
Number of sessions, max.	32
Number of accessible variables, max.	50 000 10 000
<ul><li>— Number of registerable nodes, max.</li><li>— Number of subscriptions per session, max.</li></ul>	50
— Number of subscriptions per session, max.      — Sampling interval, min.	100 ms
— Publishing interval, min.	200 ms
Number of server methods, max.	200 1115
Number of inputs/outputs per server method, max.	20
Number of impuls/outputs per server method, max.      Number of monitored items, recommended max.	4 000; for 1 s sampling interval and 1 s send interval
Number of monitored items, recommended max.      Number of server interfaces, max.	10 of each "Server interfaces" / "Companion specification" type and 20 of the type "Reference namespace"
<ul> <li>Number of nodes for user-defined server interfaces, max.</li> </ul>	15 000
Alarms and Conditions	Yes
— Number of program alarms	100
Number of alarms for system diagnostics	50
Further protocols	
• MODBUS	Yes; MODBUS TCP
S7 message functions	
Number of login stations for message functions, max.	32
number of subscriptions, max.	250
number of tags/attributes for subscriptions, max.	2 000
Program alarms	Yes
Number of configurable program messages, max.	5 000; Program messages are generated by the "Program_Alarm" block, ProDiag or GRAPH
Number of loadable program messages in RUN, max.	5 000
Number of simultaneously active program alarms	
<ul> <li>Number of program alarms</li> </ul>	600
<ul> <li>Number of alarms for system diagnostics</li> </ul>	100

<ul> <li>Number of alarms for motion technology objects</li> </ul>	160
Test commissioning functions	
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 5 engineering systems
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)
Single step	No
Number of breakpoints	8
Profiling	Yes
Status/control	
Status/control variable	Yes
Variables	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
Number of variables, max.	mpate/outpute, memory site, 255, distributed 1/56, amore, occurrent
of which status variables, max.	200; per job
of which control variables, max.	200; per job
Forcing	200, pei job
	Voc
• Forcing	Yes
Forcing, variables	Peripheral inputs/outputs
Number of variables, max.	200
Diagnostic buffer	Ver
• present	Yes
Number of entries, max.	1 000
— of which powerfail-proof	500
Traces	
<ul> <li>Number of configurable Traces</li> </ul>	4
Memory size per trace, max.	512 kbyte
Interrupts/diagnostics/status information	
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
<ul> <li>Monitoring of the supply voltage (PWR-LED)</li> </ul>	Yes
<ul> <li>Connection display LINK TX/RX</li> </ul>	Yes
Supported technology objects	
Motion Control	Yes; Note: The number of technology objects affects the cycle time of the PLC
	program; selection guide via the TIA Selection Tool
<ul> <li>Number of available Motion Control resources for technology objects</li> </ul>	1 120
<ul> <li>Required Motion Control resources</li> </ul>	
<ul> <li>per speed-controlled axis</li> </ul>	40
<ul><li>per positioning axis</li></ul>	80
— per synchronous axis	160
— per external encoder	
	80
— per output cam	80 20
•	
— per output cam	20
— per output cam  — per cam track	20 160
<ul><li>per output cam</li><li>per cam track</li><li>per probe</li></ul>	20 160
<ul> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> <li>Positioning axis</li> <li>Number of positioning axes at motion control cycle</li> </ul>	20 160 40
<ul> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> <li>Positioning axis</li> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle</li> </ul>	20 160 40
<ul> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> <li>Positioning axis</li> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> </ul>	20 160 40
<ul> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> <li>Positioning axis</li> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> </ul> Controller	20 160 40 11 14
— per output cam  — per cam track  — per probe  • Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  • PID_Compact	20 160 40 11 14  Yes; Universal PID controller with integrated optimization
<ul> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> <li>Positioning axis</li> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> </ul> Controller <ul> <li>PID_Compact</li> <li>PID_3Step</li> </ul>	20 160 40  11  14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
— per output cam — per cam track — per probe  • Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  • PID_Compact • PID_Step • PID-Temp  Counting and measuring	20 160 40  11  14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
<ul> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> <li>Positioning axis</li> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> </ul> Controller <ul> <li>PID_Compact</li> <li>PID_3Step</li> <li>PID-Temp</li> </ul> Counting and measuring <ul> <li>High-speed counter</li> </ul>	20 160 40  11  14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
— per output cam  — per cam track  — per probe  • Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  • PID_Compact  • PID_3Step  • PID-Temp  Counting and measuring  • High-speed counter  Ambient conditions	20 160 40  11  14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
— per output cam  — per cam track  — per probe  • Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  • PID_Compact  • PID_Sstep  • PID-Temp  Counting and measuring  • High-speed counter  Ambient conditions  Ambient temperature during operation	20 160 40  11  14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Yes
<ul> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> <li>Positioning axis</li> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> </ul> Controller <ul> <li>PID_Compact</li> <li>PID_3Step</li> <li>PID-Temp</li> </ul> Counting and measuring <ul> <li>High-speed counter</li> </ul> Ambient conditions Ambient temperature during operation <ul> <li>horizontal installation, min.</li> </ul>	20 160 40  11  14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Yes  -30 °C; No condensation
— per output cam — per cam track — per probe  • Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  • PID_Compact • PID_Satep • PID-Temp  Counting and measuring • High-speed counter  Ambient conditions  Ambient temperature during operation • horizontal installation, min. • horizontal installation, max.	20 160 40  11  14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Yes  -30 °C; No condensation 60 °C
<ul> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> <li>Positioning axis</li> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> </ul> Controller <ul> <li>PID_Compact</li> <li>PID_3Step</li> <li>PID-Temp</li> </ul> Counting and measuring <ul> <li>High-speed counter</li> </ul> Ambient conditions Ambient temperature during operation <ul> <li>horizontal installation, min.</li> </ul>	20 160 40  11  14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Yes  -30 °C; No condensation

<ul> <li>Installation altitude above sea level, max.</li> </ul>	5 000 m; Restrictions for installation altitudes > 2 000 m, see manual
configuration / header	
configuration / programming / header	
Programming language	
— LAD	Yes
— FBD	Yes
— STL	Yes
— SCL	Yes
— CFC	Yes
— GRAPH	Yes
Know-how protection	
<ul> <li>User program protection/password protection</li> </ul>	Yes
Copy protection	Yes
Block protection	Yes
Access protection	
<ul> <li>protection of confidential configuration data</li> </ul>	Yes
<ul> <li>Protection level: Write protection</li> </ul>	Yes
<ul> <li>Protection level: Read/write protection</li> </ul>	Yes
<ul> <li>Protection level: Write protection for Failsafe</li> </ul>	No
<ul> <li>Protection level: Complete protection</li> </ul>	Yes
User administration	Yes; device-wide
programming / cycle time monitoring / header	
• lower limit	adjustable minimum cycle time
• upper limit	adjustable maximum cycle time
Dimensions	
Width	100 mm
Height	117 mm
Depth	75 mm
Weights	
Weight, approx.	265 g

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